

Enhancing Cyber Attack Autonomy Through Multi-Agent Reinforcement Learning

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The Rise of Autonomous Vulnerability Discovery



**DARPA AI Cyber
Challenge (AIxCC)**
Prove that AI-driven
vulnerability detection
and patching work.



Aug 2025

1. AUTOMATION

AI handles tasks

2. ORCHESTRATION

AI coordinates operations

3. EXPLOITATION AT SCALE

AI discovers and weaponizes

4. ECOSYSTEM DISRUPTION

Incentives and systems break



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AI-Orchestrated Espionage

First AI orchestrated campaign disclosed by Anthropic.



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Model discovers 500+ high-severity vulnerabilities in 48h.

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Internet Bug Bounty overwhelmed by AI reports.

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Claude Mythos Preview
Anthropic cancels launch of Claude Mythos.

Apr 2026

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Agents forget earlier findings during long campaigns

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CTF Benchmark ≠ production

Winning a benchmark is not the same as breaching a real target

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Speed creates a detectable signature

Machine-speed actions look nothing like a human operator

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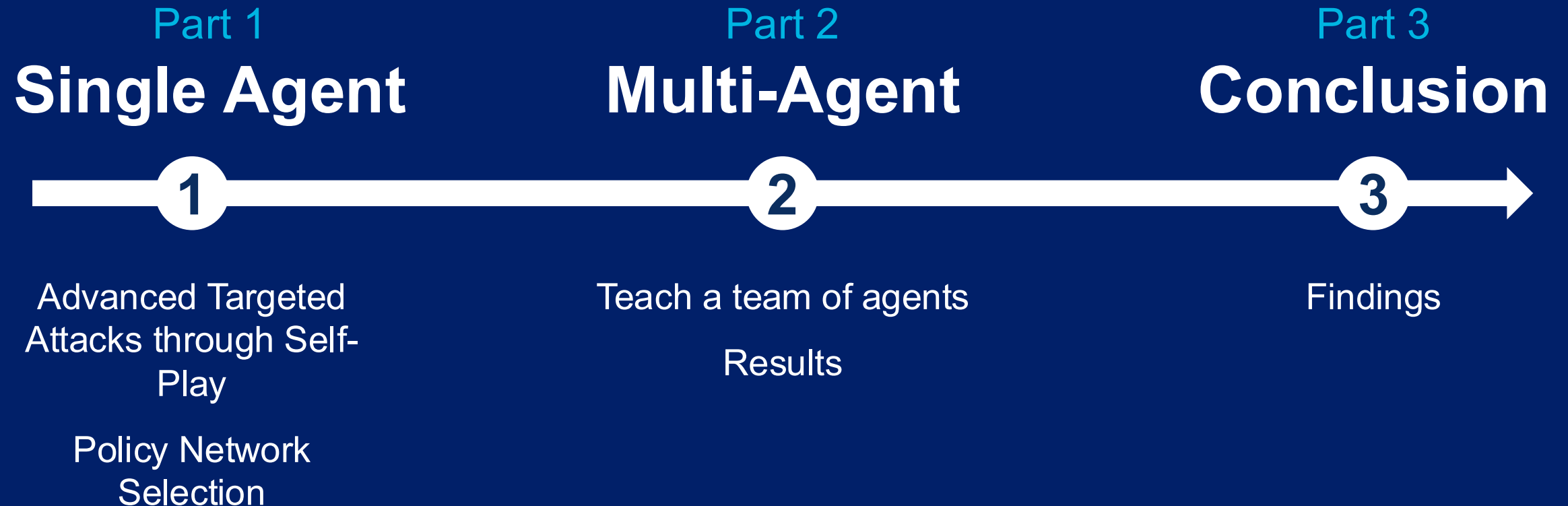
AI Agents act greedy

Agents chase the quickest win and get stuck in dead ends

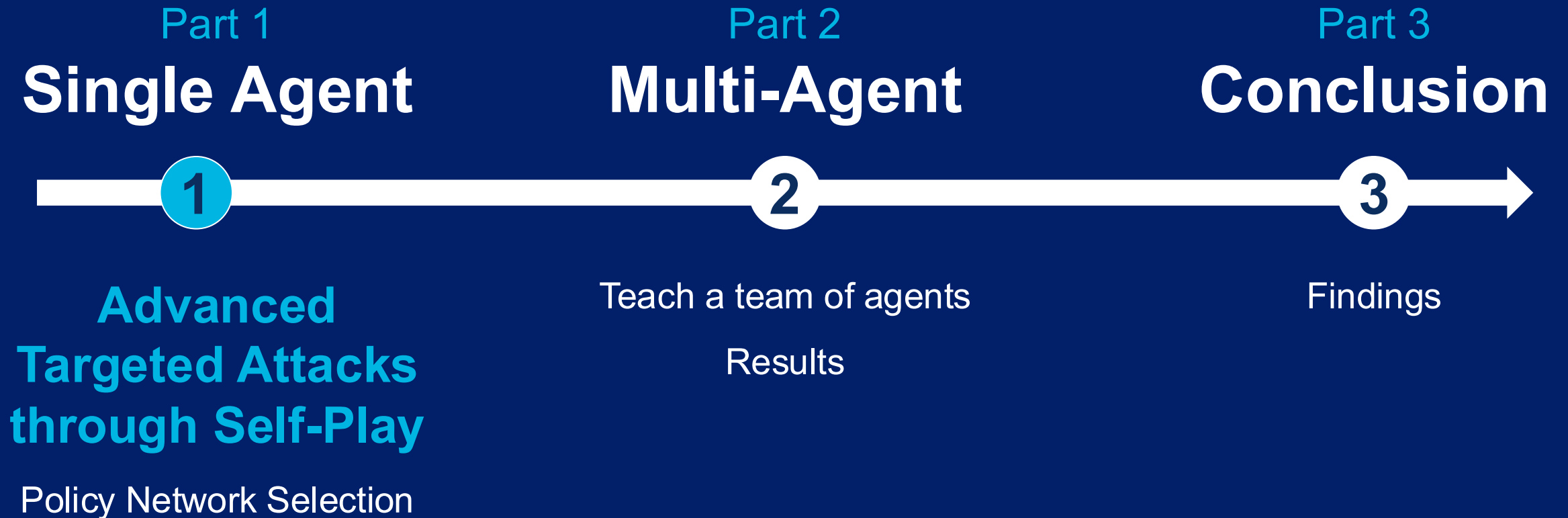
This presentation asks

What If Agents Escaped the Greediness by Working Together?

From One Agent to a Team

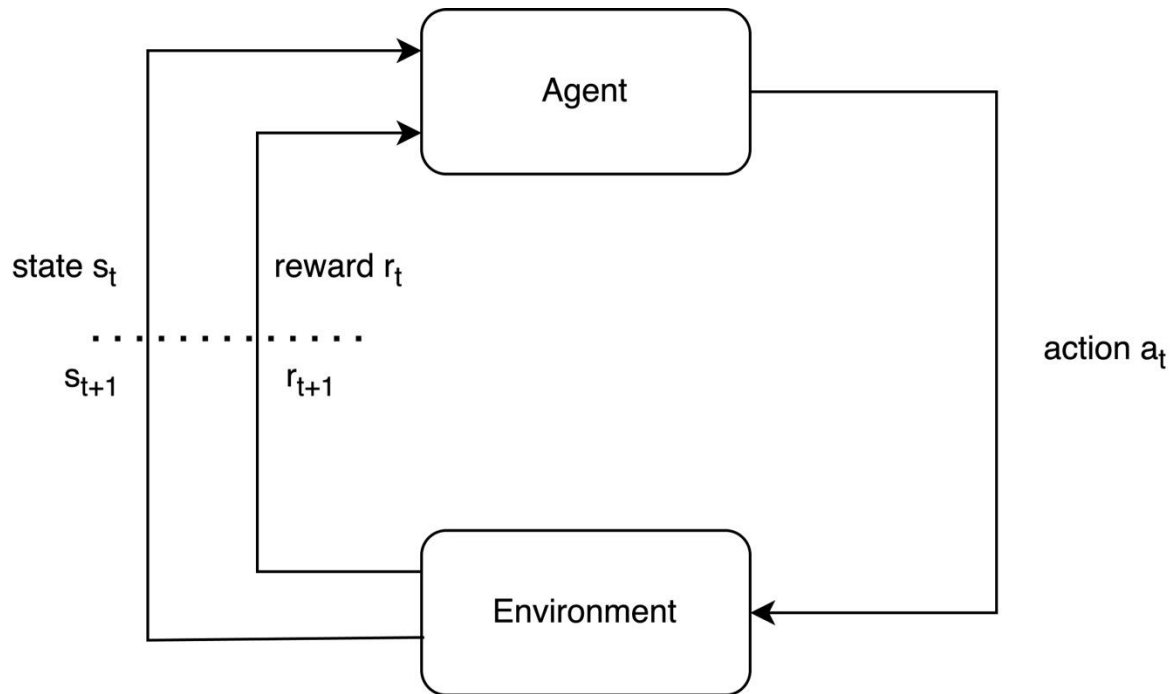


From One Agent to a Team



How to Learn Through Self-Play?

Introduction to Reinforcement Learning (RL)



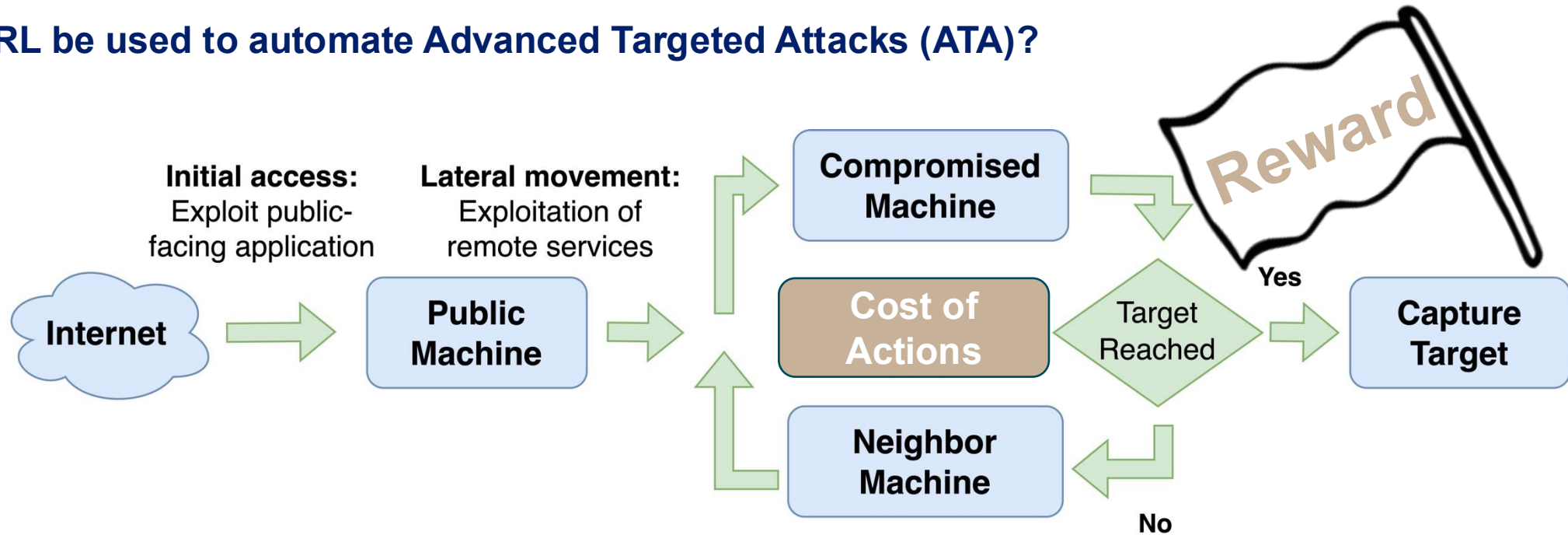
RL control loop

Use **Reinforcement Learning (RL)** when:

- **Sequential** decision-making is required
- **No labelled data**, but a reward signal is available
- Environment **dynamics are uncertain** or complex

Problem

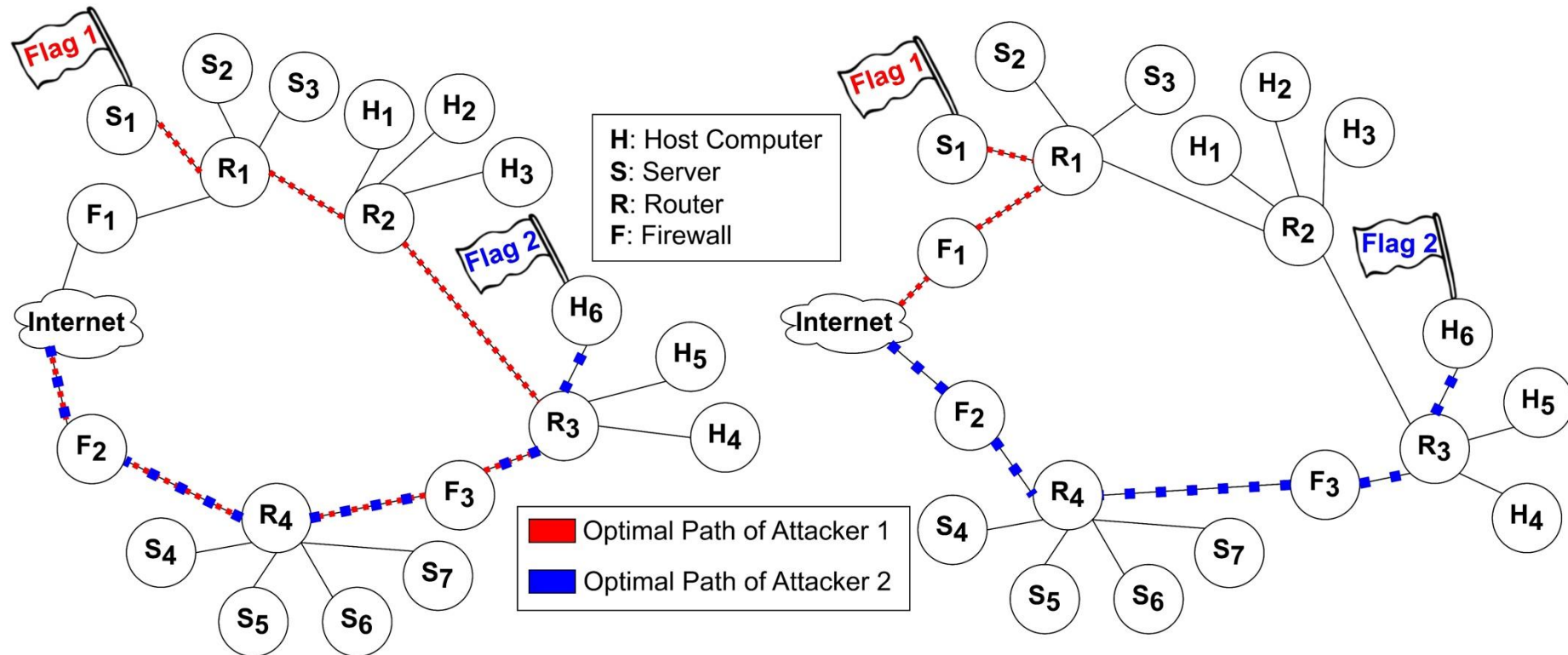
Can RL be used to automate Advanced Targeted Attacks (ATA)?



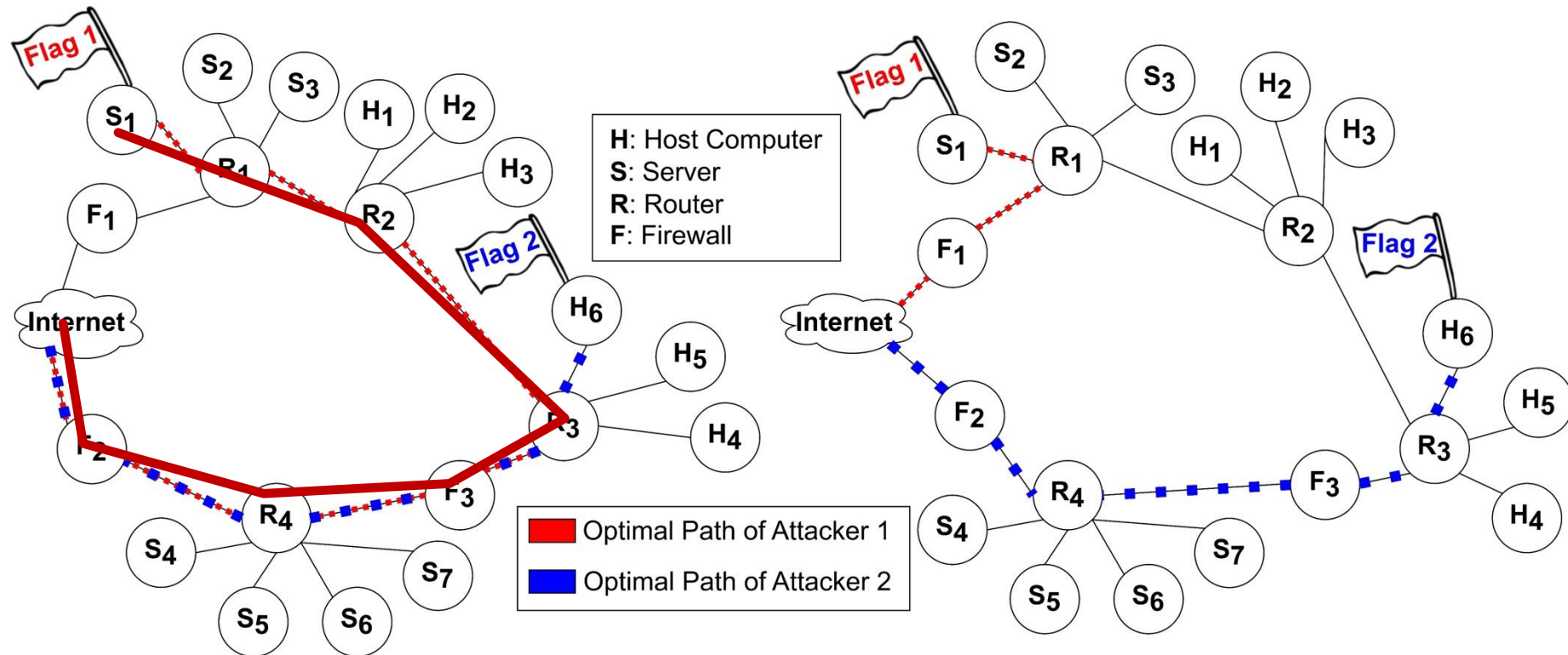
Attack graph starting from the Internet.

Sequential Actions / No training Data

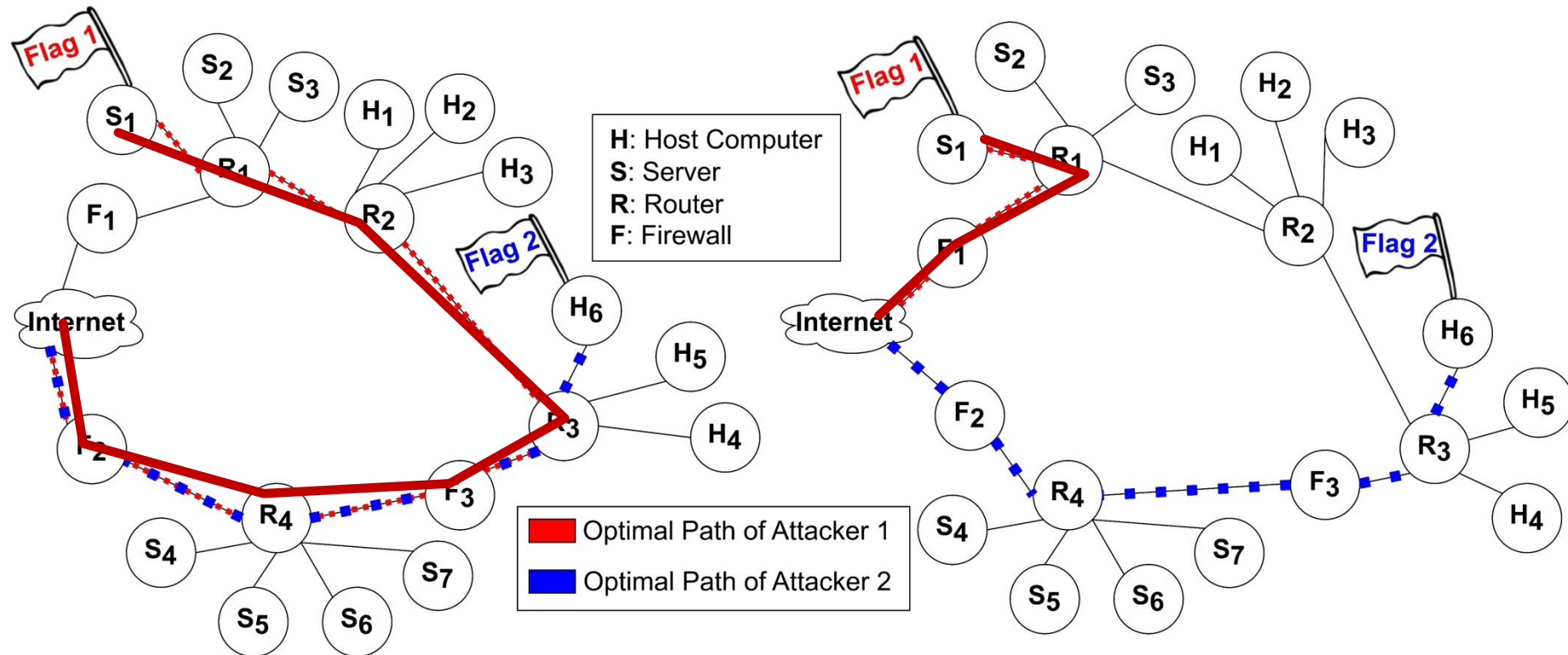
Can an Attacker Navigate Complex Networks?



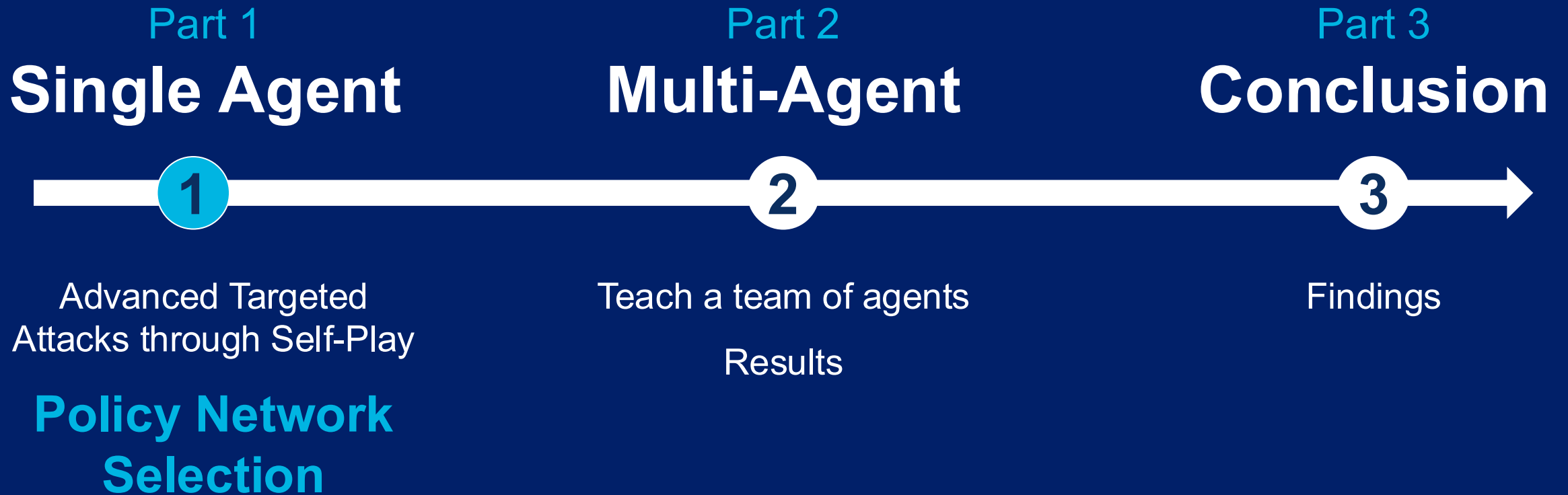
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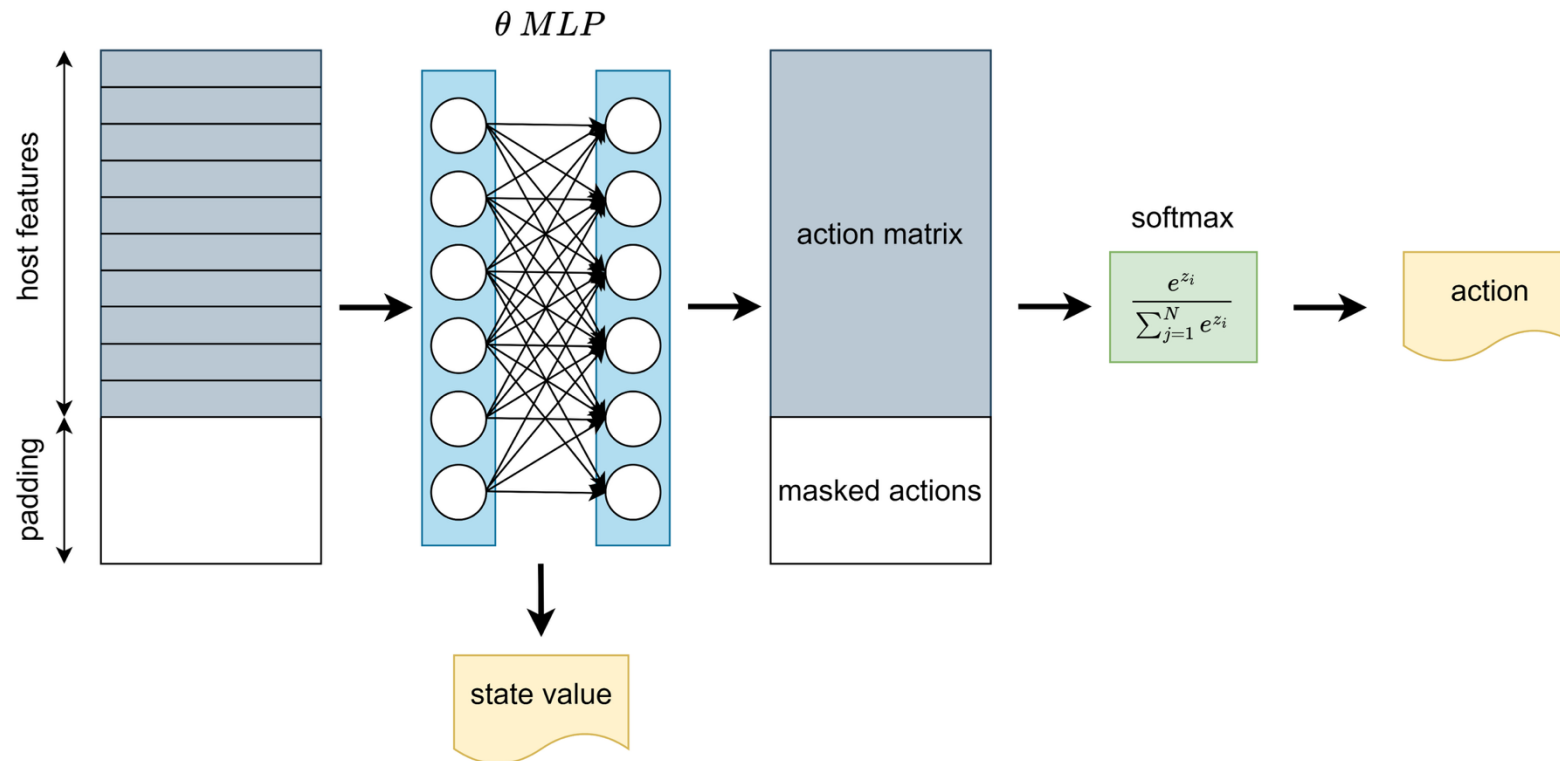
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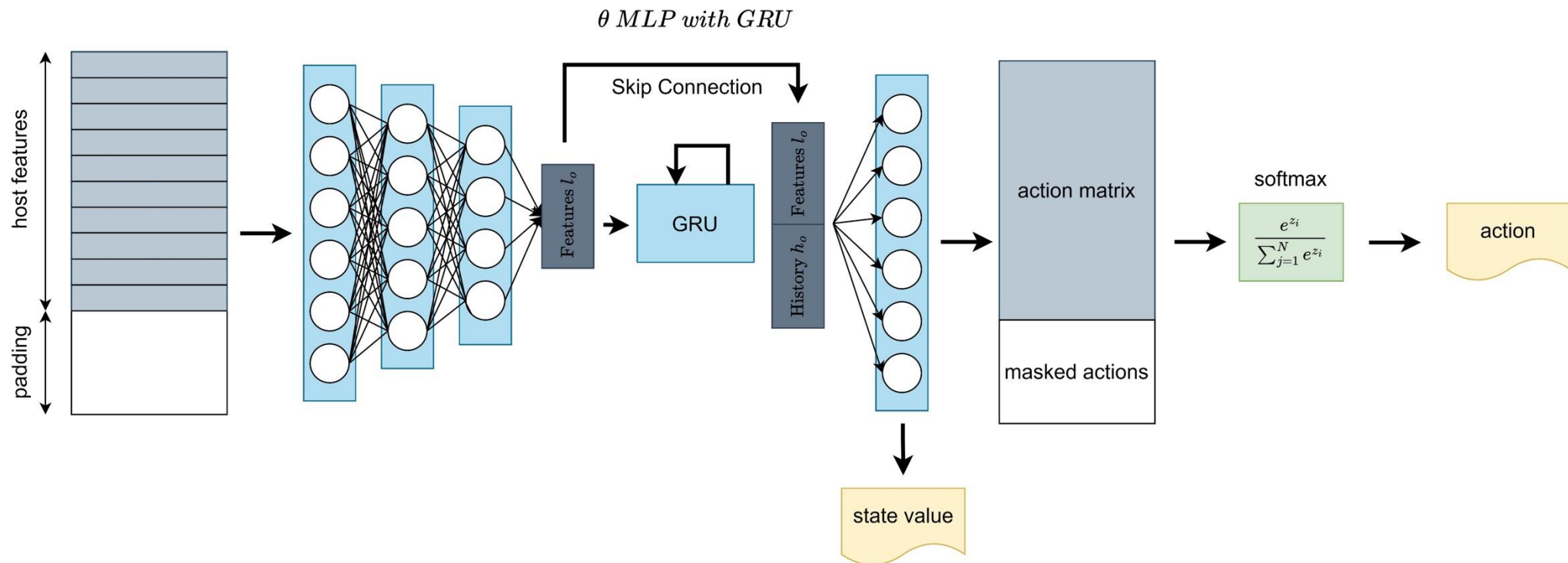
From One Agent to a Team



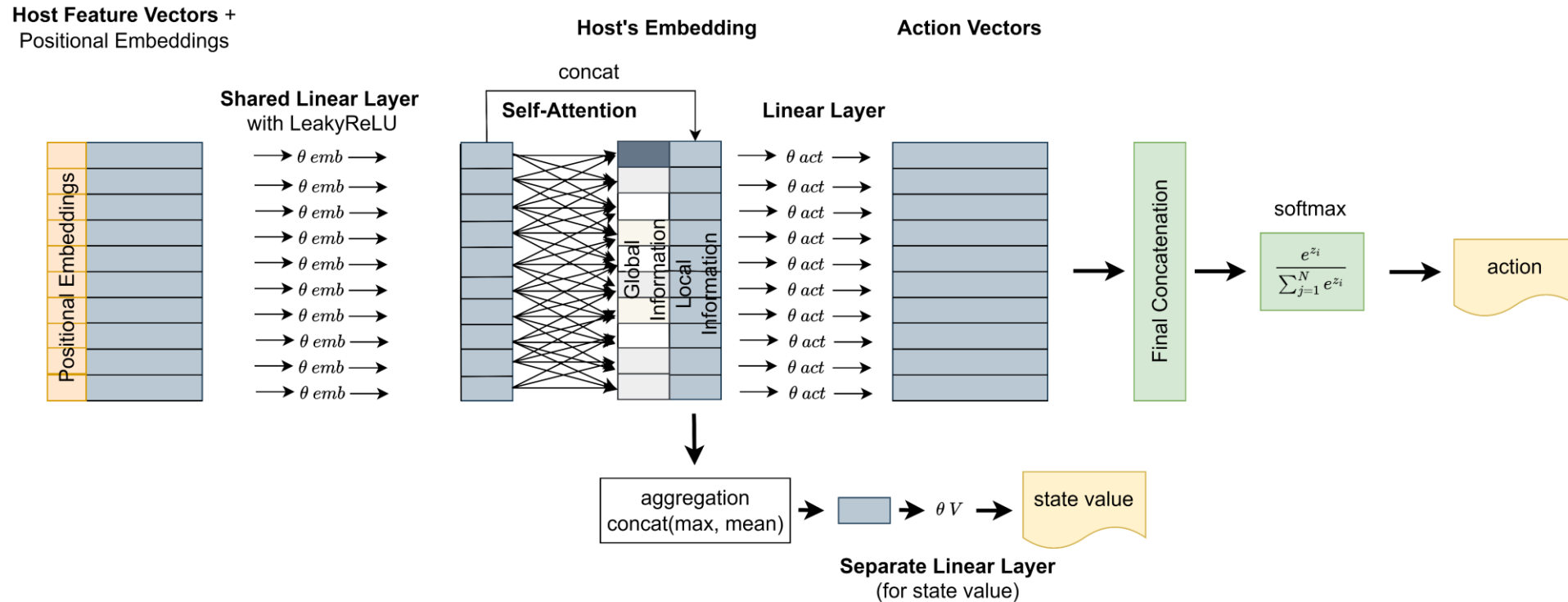
Can a Feed-Forward Neural Network Be Used for Autonomous Cyber Agents?



Can a Memory Module Help to Navigate Complex Scenarios?

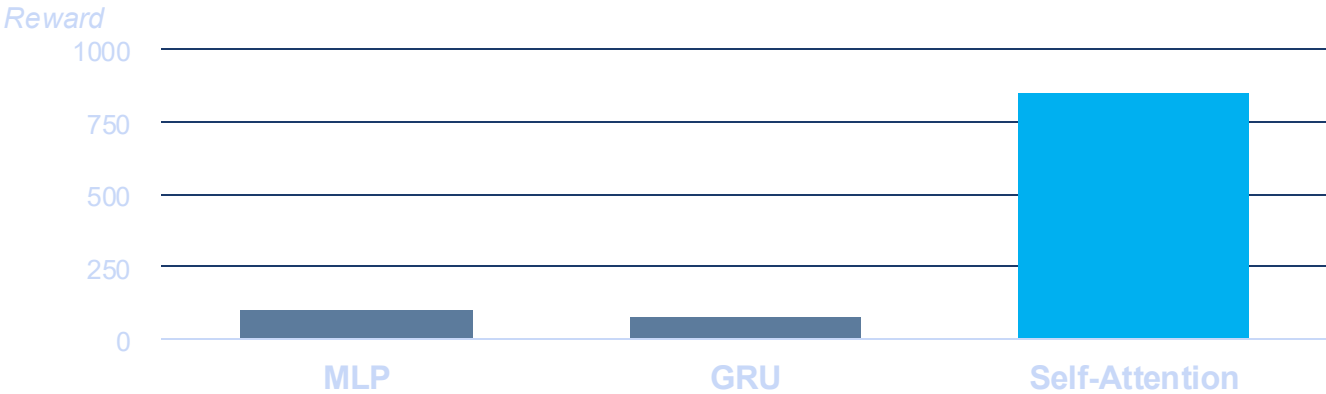


Can a Memory Module with Attention Help to Navigate Complex Scenarios?



Implementation of a Self-Attention Mechanism to realize the memory component to leverage local and global information.

Results: Single Agent Training



Final rolling-mean reward at ~175k training steps (Fig. 6, paper).

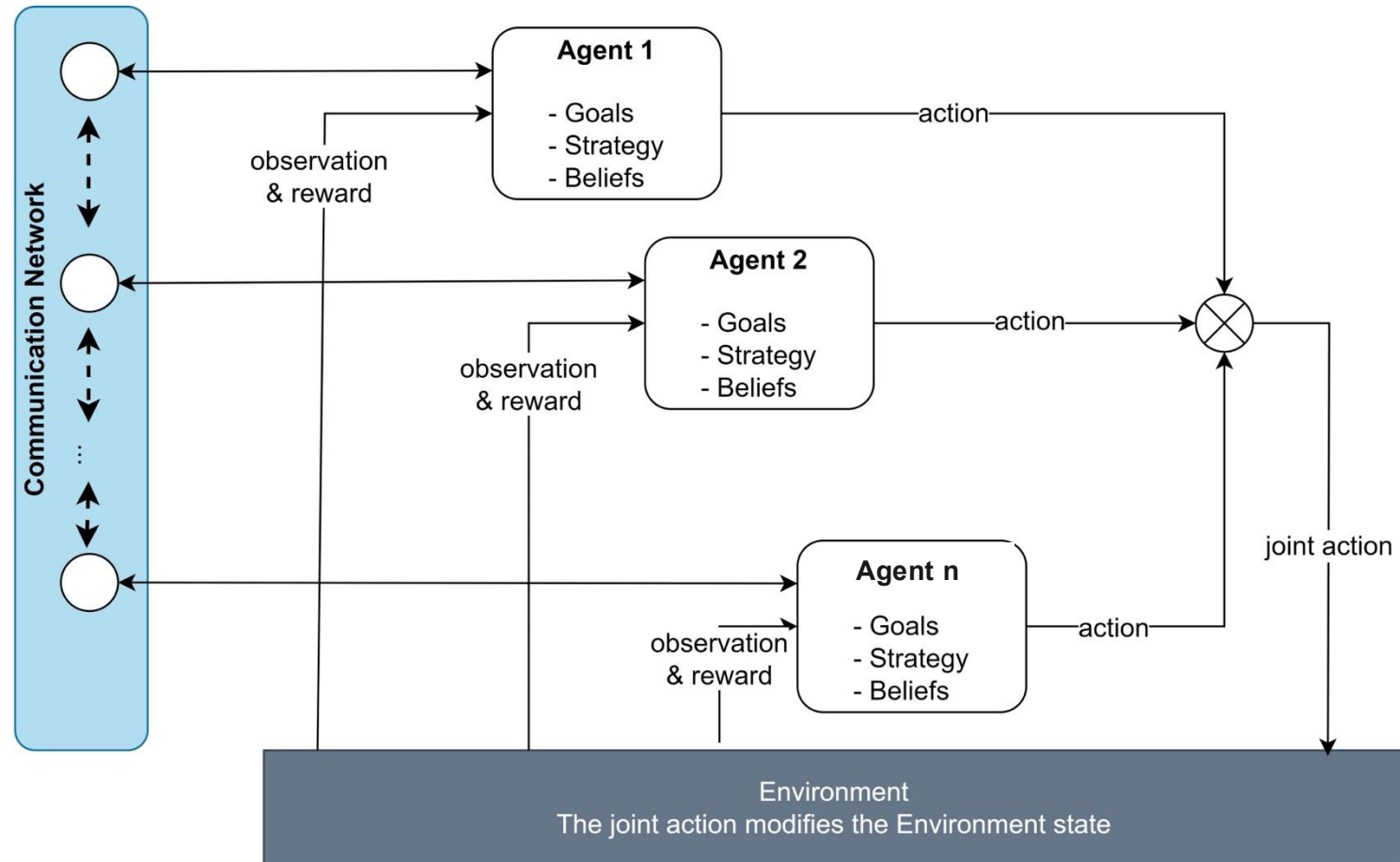
Action distribution & convergence			
	Entropy ↑	Kurtosis ↓	Status
MLP	2.33	8.54	Plateau
GRU	2.70	6.16	Plateau
Self-Attention	2.96	5.17	Solved (grokked)

From One Agent to a Team



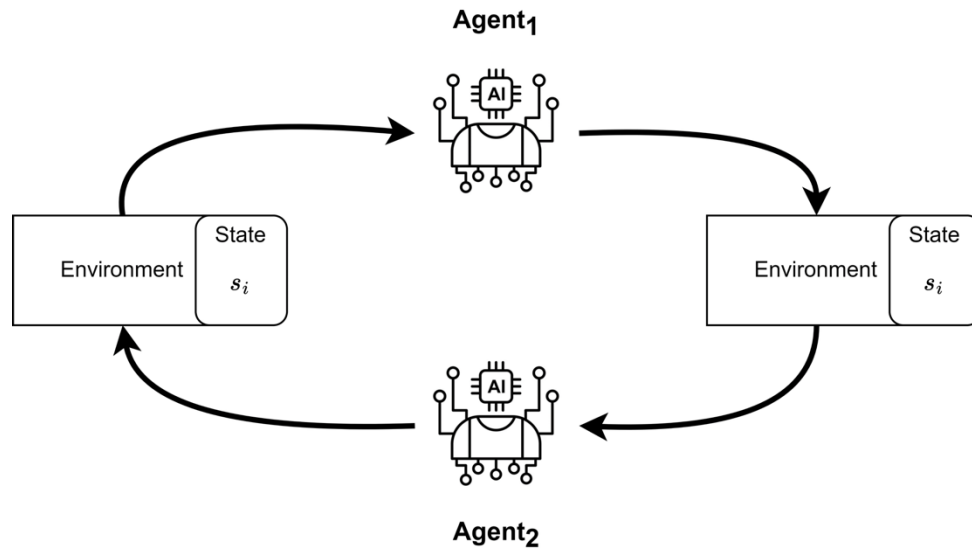
Multi-Agent Reinforcement Learning Loop

How to train multiple agents in a shared environment?



Environment Non-Stationarity

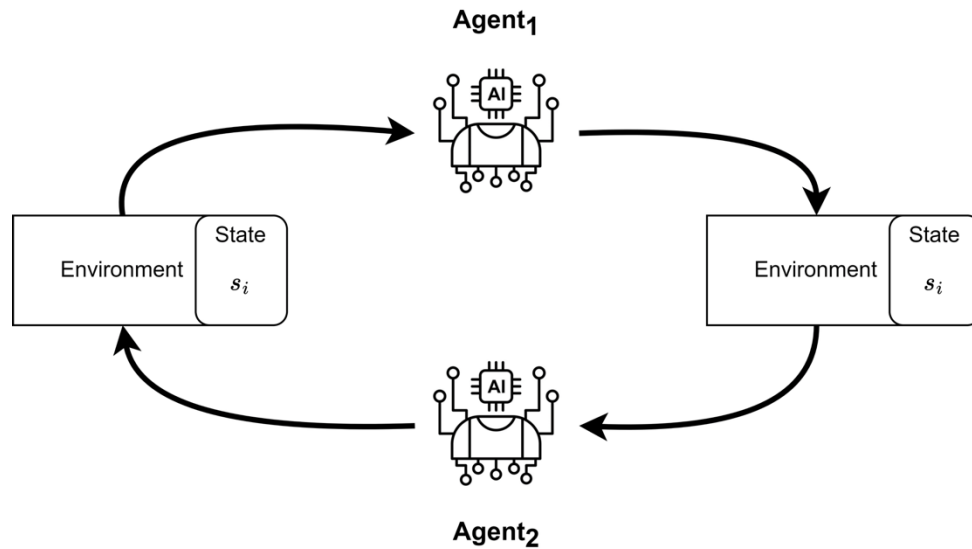
How do agents in a self-play environment reach a cooperative equilibrium despite the observation corruption caused by simultaneous agent execution?



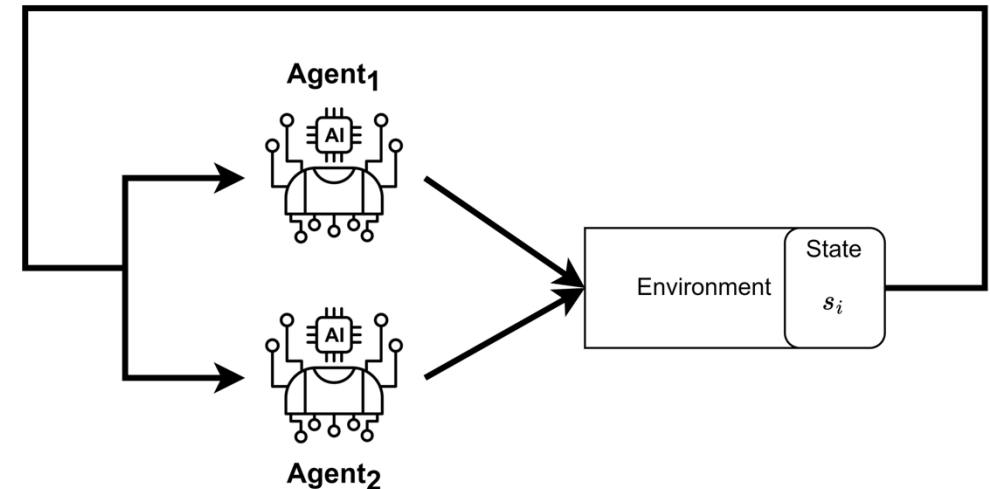
Game model as Agent Environment Cycle (AEC)

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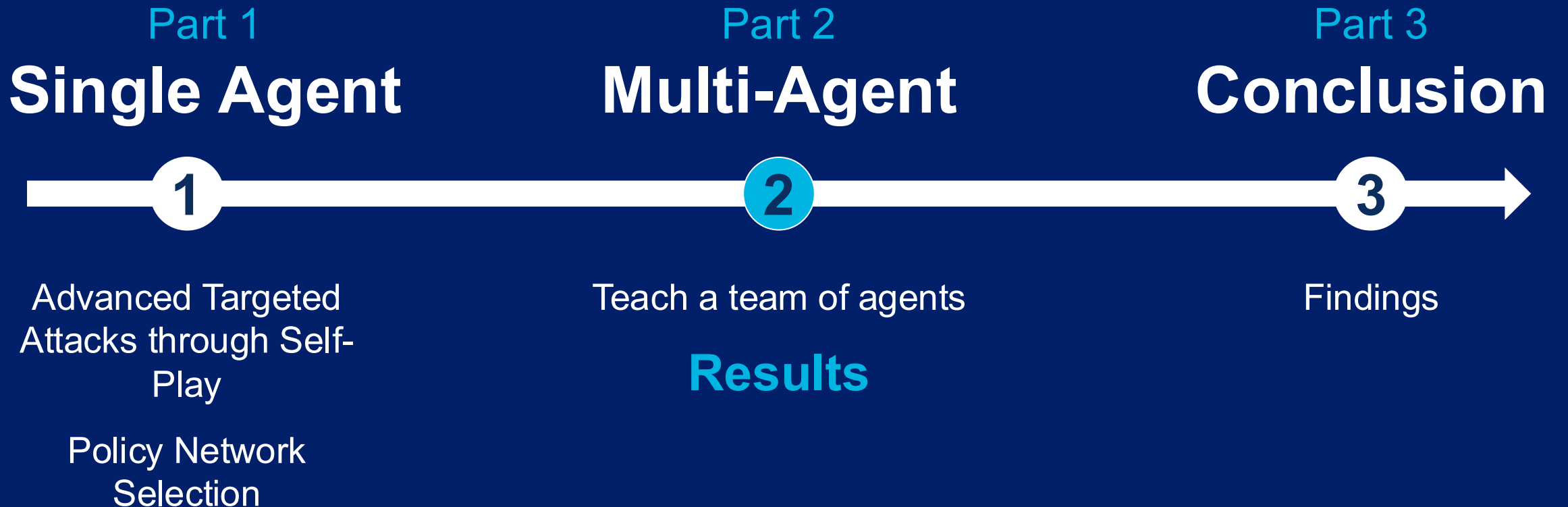


Partially Observable Stochastic Games (POSGs) modelled as Parallel Game

The Effect of Non-Stationarity on the Memory Module



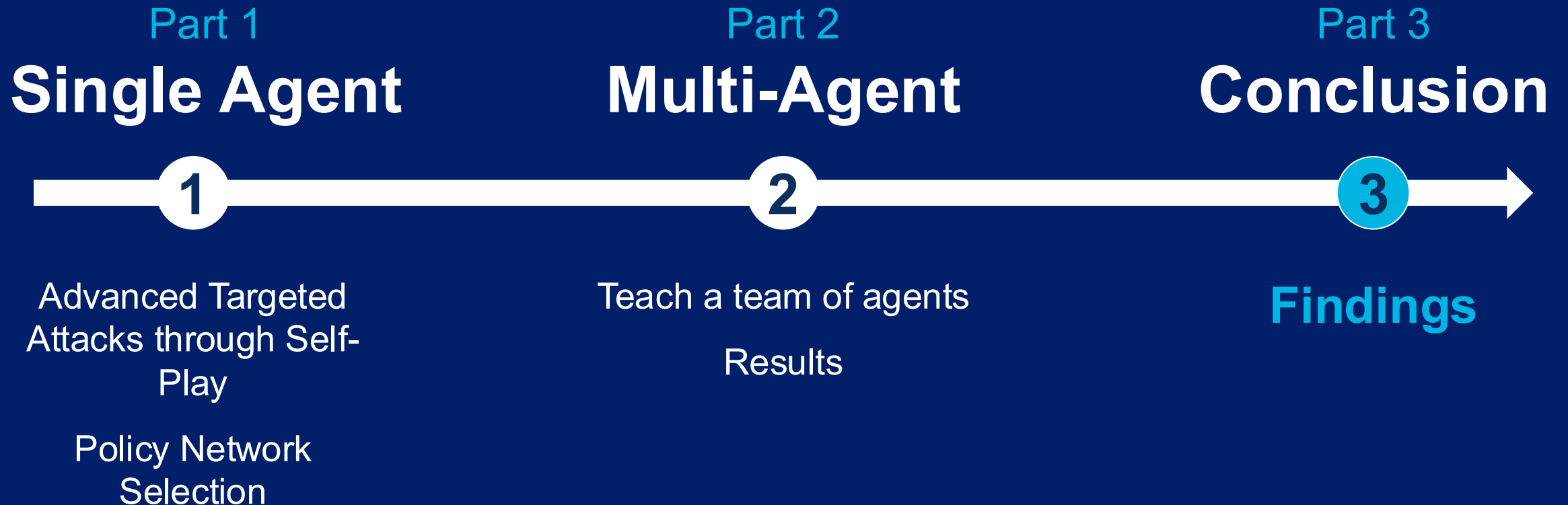
From One Agent to a Team



The Scalability Bottleneck

Name	Subnets	Actions	States	SARL PPO	MASAC (3 Agents)	Step Limit
Tiny	4	18	576	193.23 ± 0.68 (Reward) 6.78 ± 0.36 steps	58.51 ± 0.05 8.82 ± 0.38 steps	1,000
Small	5	72	4,576	184.83 ± 1.41 (Reward) 8.48 ± 0.19 steps	Did not Converge	1,000
Medium	6	192	3.9×10^5	181.87 ± 2.64 (Reward) 9.15 ± 0.47 steps	Did not Converge	2,000
Large	8	322	4.5×10^6	-89.93 ± 1.25 (Reward) 100 ± 0 steps	Did not Converge	5,000

From One Agent to a Team



Conclusion: What Can We Learn?



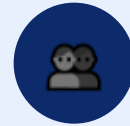
SARL Works

Needs entropy reg. + latent tuning



Memory Matters

Encoder + Memory + Controller



MARL: Promise vs. Scale

Non-stationarity kills scaling

💡 **Bottom Line:** MARL enables coordinated attacks, but scalability beyond tiny networks remains the critical open problem.

Thank You



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